

### Recommended Alternative (Safety Study)

The initial recommended roundabout configuration from the Safety Study included the following lane assignments:

• **EB**: LTR

• **WB:** LT / TR (with outside lane reduction downstream of the roundabout)

NB: LT / RSB: LTR



During the DSRT stakeholder presentation, concerns were raised regarding the two westbound through lanes entering the roundabout and the subsequent lane reduction. ODOT'S ECAT cannot account for the lane reduction downstream of the roundabout. Results were thought to be misleading. Stakeholders felt that capacity was being prioritized over safety.

#### **Operational Goals**

The Safety Study's recommended alternative met the operational goals outlined in Section 5.9 of ODOT's *Analysis and Traffic Simulation Manual (OATS)*.

The operational goals for intersection analyses (AWSC, TWSC, Roundabout, Signalized) is to operate at:

Result	Operational Goal
Intersection LOS	D or better <sup>1</sup>
Approach LOS	E or better
Control LOS	E or better
v/c <sup>2</sup>	All movements < 1.0 with ≤ 0.93 preferred.
QSR <sup>3</sup>	All movements < 1.0 from HCS analysis, otherwise TransModeler may be needed to determine if queuing impacts upstream intersections.

<sup>1:</sup> A LOS E may be acceptable at locations where a vulnerable road user project on a low-speed facility is implemented if the Build condition does not have a significant adverse impact on the safety and operations within the study area; 2:  $v/c = Volume-to-Capacity\ ratio$ ; 3: QSR = Queue-Storage ratio

**Level of Service (LOS)** is defined by the *Highway Capacity Manual (HCM)*, which provides LOS thresholds for both **un-signalized** and **signalized** intersections. Roundabouts are typically evaluated under the un-signalized delay category. To meet a minimum acceptable LOS of **E or better**, average delays should remain below:

- 50 seconds per vehicle for un-signalized conditions, and
- 80 seconds per vehicle for signalized conditions.

LOS	<b>Un-Signalized Delay</b>	Signalized Delay
Α	≤ 10 sec/veh	≤ 10 sec/veh
В	> 10-15 sec/veh	> 10-20 sec/veh
С	> 15–25 sec/veh	> 20-35 sec/veh
D	> 25-35 sec/veh	> 35-55 sec/veh
Е	> 35-50 sec/veh	> 55-80 sec/veh
F	> 50 sec/veh	> 80 sec/veh

ODOT District 4 has established a maximum operational delay target of 80 seconds per vehicle to balance safety and traffic performance

#### **Traffic Volumes**

Updated turning movement counts (TMCs) were collected in **April 2025**. Compared to 2019 TMC, the intersection experienced a **3% increase** in overall volume. Design Hour Factors and a **0.05% growth rate** along SR 14 were applied to project volumes for:

• Opening Year: 2029

• Design Year: 2049

The Cleveland Road detour was incorporated, redirecting all traffic from Cleveland Road to Infirmary Road for SR 14 access.

#### **Considered Alternatives**

The following roundabout alternatives were evaluated:

- Alt 1
  - o EB: 1 LTR
  - o WB: 1 LTR
  - o NB: 1 LTR
  - o SB: 1 LTR
- Alt 2
  - o EB: 1 LTR
  - o WB: 1 LT / 1 R
  - o NB: 1 LT / 1 R
  - o SB: 1 LTR
- Alt 3
  - o EB: 1 LTR
  - o WB: 1 L / 1 TR
  - o NB: 1 LT / 1 R
  - o SB: 1 LTR
- Alt 4 (\*Recommended by Safety Study\*)
  - o EB: 1 LTR
  - o WB: 1 LT / 1 TR (with downstream outside lane reduction)
  - o NB: 1 LT / 1 R
  - o SB: 1 LTR

#### **Capacity Analysis**

Capacity was analyzed using **Highway Capacity Software (HCS) 2025 and 2026**.

Summary tables for both the Opening Year (2029) and Design Year (2049) are attached.

### • 2049 Analysis:

Only **Alternatives 3 and 4** meet the District's 80 sec/veh delay target. Due to safety concerns with Alt 4, **Alternative 3** is selected as the **preferred long-term solution**.

#### 2029 Analysis:

Alternatives 2, 3, and 4 all meet the delay target. Alternative 2 is expected to

provide acceptable performance for approximately **five years**, as shown in the attached sensitivity analysis table for Alt 2.

#### Conclusion

To balance safety and operational performance:

- Construct the roundabout footprint for Alternative 3 (long-term solution).
- Implement lane assignments from Alternative 2 at opening to optimize operations.

Movements	E	B: LTR / WB: LTF	Detour (ALT 1) R / NB: LTR / SB: N + E S	TR	EB	LTR / WB: LT-F	Detour (ALT 2) R / NB: LT-R / SB:  N	LTR	EE	S: LTR / WB: L-TR	Detour (ALT 3) / NB: LT-R / SB: N H E S	TR		R / WB: LT-TR (SI	N E S			R / WB: LT-TR (70	ur (ALT 4-70/30 0/30) / NB: LT-R /		Movements
	LOS	Delay (sec/veh)	95th Queue	QSR	LOS	Delay (sec/veh)	95th Queue	QSR	LOS	Delay (sec/veh)	95th Queue	QSR	LOS	Delay (sec/veh)	95th Queue	QSR	LOS	Delay (sec/veh)	95th Queue	QSR	
EBL																					EBL
EBT EBR	С	22.6	222	-	С	22.6	222	-	С	22.6	222	-	С	22.6	222	-	С	22.6	222	-	EBT EBR
EB Approach	C	22.6			C	22.6			C	22.6				22.6			С	22.6			EB Approach
WBL	C	22.0		-	C	22.0			A	6.9	26		F	49.8	457	_	D	28.8	290	_	WBL
WBT	F	177.8	1132	_	F	114.1	846	_	F	48.5	450			45.0	437			20.0	230		WBT
WBR		27710	1101		А	4.7	5	-		.0.0	.50		А	6.9	27	-	A	8.6	46	-	WBR
WB Approach	F	177.8	-	-	F	109.7	-	-	Е	40.0	-	-	Е	41.2	-	-	С	22.7	-	-	WB Approach
NBL					С	16.3	113	0.45	С	16.3	113	0.45	С	16.3	113	0.45	С	16.3	113	0.45	NBL
NBT	E*	50.5	341	1.36	А	8.0	24	0.10	А	8.0	24	0.10	А	8.0	24	0.10	А	8.0	24	0.10	NBT
NBR																					NBR
NB Approach	E*	50.5	-	-	В	14.0	-	-	В	14.0	-	-	В	14.0	-	-	В	14.0	-	-	NB Approach
SBL																					SBL
SBT	D	30.4	95	-	D	30.4	95	-	С	18.4	61	-	С	18.4	61	-	С	18.4	61	-	SBT
SBR																					SBR
SB Approach	D	30.4	-	-	D	30.4	-	-	С	18.4	-	-	С	18.4	-	-	С	18.4	-	-	SB Approach
Intersection	F	95.8		-	E*	58.2	-	-	D	27.6	-	-	D	28.2	-	-	C	20.3	-	-	Intersection
Comments		vement LOS F bach LOS F	erational goals		Does NOT satisfy D4's operational goals - WB T movement LOS F - WB approach LOS F				Satisfies operational goals in OATS				*WB Lane Utilization (80% inside / 20% outside)  WB Lane reduction downstream of roundabout  **(Recommended in Safety Study)**				*WB Lane rec	Comments			
O													Predicted Cr - Injury: 0. - Property	rash Rates			Predicted Cr - Injury: 0.0 - Property	ash Rates			- °S

Result	Operational Goal
Intersection LOS	D or better <sup>1</sup>
Approach LOS	E or better
Control LOS	E or better
v/c²	All movements < 1.0 with ≤ 0.93 preferred.
QSR <sup>3</sup>	All movements < 1.0 from HCS analysis, otherwise TransModeler may be

	Un-Signal	lized Delay LOS
	LOS A: ≤ 10 sec/veh	LOS D: > 25-35 sec/veh
	LOS B: > 10-15 sec/veh	LOS E: > 35-50 sec/veh
	LOS A: ≤ 10 sec/veh LOS B: > 10–15 sec/veh LOS C: > 15–25 sec/veh	LOS F: > 50 sec/veh
,	* D4 has set a target of 80	sec/veh as our operational goal

Signal	lized Delay LOS
LOS A: ≤ 10 sec/veh	LOS D: > 35-55 sec/veh
LOS B: > 10-20 sec/veh	LOS E: > 55-80 sec/veh
LOS C: > 20-35 sec/veh	LOS F: > 80 sec/veh

Movements		EB: LTR / WB: LT	T - Detour (ALT 1  TR / NB: LTR / SE	t LTR	*		Detour (ALT 2)  N  F E  S  S  S  S  S  S  S  S  S  S  S  S  S	1	*	LTR / WB: L-TR	Detour (ALT 3)  / NB: LT-R / SB: L  N  E S	1 2	EB: LTR	Delay	(20) / NB: LT-R /	SB: LTR	EB: LTI	R / WB: LT-TR (7)	N	SB: LTR	Movements
	LOS	(sec/veh)	95th Queue	QSR	LOS	(sec/veh)	95th Queue	QSR	LOS	(sec/veh)	95th Queue	QSR	LOS	(sec/veh)	95th Queue	QSR	LOS	(sec/veh)	95th Queue	QSR	
EBL																					EBL
EBT	С	16.9	156	-	С	16.9	156	-	С	16.9	156	-	С	16.9	156	-	С	16.9	156	-	EBT
EBR	С	16.9			C	16.9			С	16.0				16.9			6	16.9			EBR
EB Approach WBL	Ĺ	16.9	-	-	C	16.9	-	-	A	16.9 6.6	- 24	-	D	32.5	325	-	C C	21.6	215	-	EB Approach WBL
WBT	E	125.9	850	-	E*	72.2	602	_	D	32.1	323		U	32.3	323	-	C	21.0	213	-	WBT
WBR		123.3	030		A	4.7	5	_		32.1	323		Α	6.6	24	-	А	8.1	40	-	WBR
WB Approach	F	125.9	-	-	E*	69.3	-	-	D	26.9	-	-	D	27.3	-	-	С	17.5	-	-	WB Approach
NBL					В	14.5	100	0.40	В	14.5	100	0.40	В	14.5	100	0.40	В	14.5	100	0.40	NBL
NBT	E	38.5	291	1.16	Α	7.5	24	0.10	Α	7.5	24	0.10	Α	7.5	24	0.10	А	7.5	24	0.10	NBT
NBR																					NBR
NB Approach	E	38.5	-	-	В	12.6	-	-	В	12.6	-	-	В	12.6	-	-	В	12.6	-	-	NB Approach
SBL																					SBL
SBT	С	24.4	79	-	С	24.4	79	-	С	15.9	53	-	С	15.9	53	-	С	15.9	53	-	SBT
SBR																					SBR
SB Approach	C F*	24.4 68.0	-	-	С	24.4	-	-	С	15.9	-	-	С	15.9 20.0	-	-	С	15.9 16.0	-	-	SB Approach
Comments	Does NOT satisfy D4's operational goals  - WB T movement LOS F  - WB approach LOS F  - Intersection LOS F  - NB QSR > 1.0  Predicted Crash Rates  - Injury: 0.64  - Property Damage: 3.13  - Total Crashes: 3.77 (4.34 reduction)				- WB T mov - WB appro Predicted Cr - Injury: 0.4 - Property	vement LOS F pach LOS F ash Rates		<u> </u>	Satisfies operational goals in OATS  Predicted Crash Rates - Injury: 0.65 - Property Damage: 3.73 - Total Crashes: 4.38 (3.73 reduction)				*WB Lane Utilization (80% inside / 20% outside)  WB Lane reduction downstream of roundabout  **(Recommended in Safety Study)**  Predicted Crash Rates - Injury: 0.65 - Property Damage: 3.73 - Total Crashes: 4.38 (3.73 Reduction)				*WB Lane Utilization (70% inside / 30% outside)  WB Lane reduction downstream of roundabout  **(Recommended in Safety Study)**  Predicted Crash Rates - Injury: 0.65 - Property Damage: 3.73 - Total Crashes: 4.38 (3.73 Reduction)				Comments

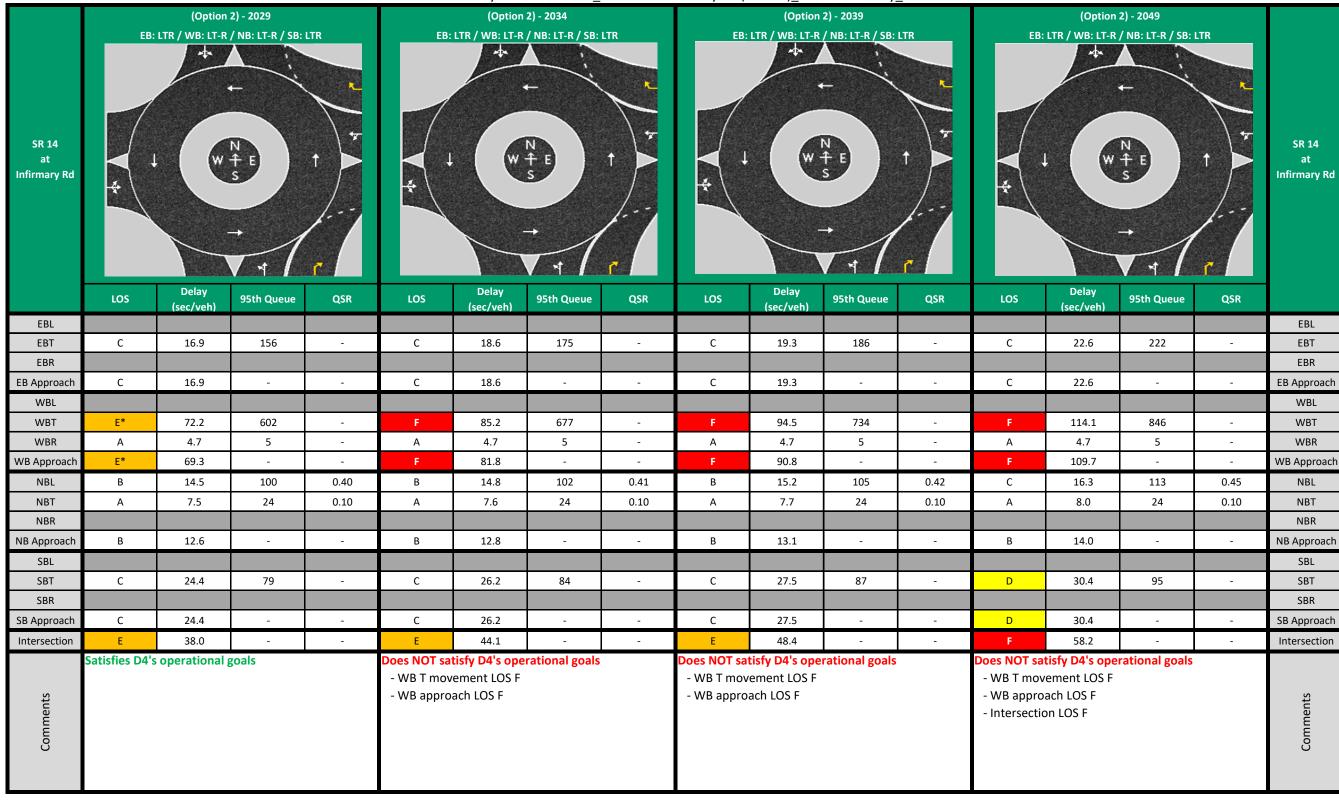
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LOS D: > 25-35 sec/veh
LOS E: > 35-50 sec/veh
LOS F: > 50 sec/veh

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Signa	lized Delay LOS
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LOS C: > 20-35 sec/veh	LOS F: > 80 sec/veh



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Un-Signalized Delay LOS		
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LOS B: > 10-15 sec/veh	LOS E: > 35-50 sec/veh	
LOS C: > 15-25 sec/veh	LOS F: > 50 sec/veh	

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Signalized Delay LOS		
LOS A: ≤ 10 sec/veh	LOS D: > 35-55 sec/veh	
LOS B: > 10-20 sec/veh	LOS E: > 55-80 sec/veh	
LOS C: > 20-35 sec/veh	LOS F: > 80 sec/veh	